#### **Lesson 13**

Stokes' Theorem, Curl, 3D Flow Along

### Lesson 8: Measuring the Net Flow of a Vector Field ACROSS a Closed Curve

Let C be a closed curve with a counterclockwise parameterization. Then the net flow of the vector field *ACROSS* the closed curve is measured by:

```
C
            b
            a
      =\oint_{\mathsf{C}} -\mathsf{n}(\mathsf{x},\mathsf{y}) \mathsf{d} \mathsf{x} + \mathsf{m}(\mathsf{x},\mathsf{y}) \mathsf{d} \mathsf{y}Field(x,y) outerunitnormal ds

      Field(x(t),y(t)) (y'(t), x'(t))dt

\pmb{\mathfrak{f}}\int\pmb{\vartheta}
```
Let region R be the interior of C. If the vector field has no singularities in R, then we can use Gauss-Green:

$$
\lim_{R \to \infty} \frac{\partial \mathbf{m}}{\partial \mathbf{x}} + \frac{\partial \mathbf{n}}{\partial \mathbf{y}} \mathbf{y} \, d\mathbf{x} \, d\mathbf{y}
$$
\nLet  $\text{div}\, \text{Field}(x, y) = \frac{\partial \mathbf{m}}{\partial x} + \frac{\partial \mathbf{n}}{\partial y}$ .  
\n
$$
= \iint \text{div}\, \text{Field}(x, y) \, dx \, dy
$$

```
R
=\iint divField(x, y) dx dy
```
### Lesson 8 : The Net Flow of A Vector Field ACROSS a Closed Curve:

Let C be a closed curve parameterized counterclockwise. Let Field(x,y) be a vector field with no singularities on the interior region R of C. Then:

$$
\oint_{C} Field(x, y) \bullet outer unit normal ds = \iint_{R} divField(x, y) dx dy
$$

This measures the net flow of the vector field *ACROSS* the closed curve.

We define the divergence of the vector field as:  
divField(x, y) = 
$$
\frac{\partial m}{\partial x} + \frac{\partial n}{\partial y} = D[m[x, y], x] + D[n[x, y], y]
$$

Lesson 12: The Net Flow of A Vector Field ACROSS a Closed Surface:

Let R be a solid in three dimensions with boundary surface (skin) C with no singularities on the interior region R of C. Then the net flow of the vector field Field(x,y,z) *ACROSS* the closed surface is measured by:

$$
\oiint_{C} \text{Field}(x, y, z) \cdot \text{outernormal } dA
$$
\n
$$
= \iiint_{R} \text{divField}(x, y, z) \, dx \, dy \, dz
$$

Let Field(x, y, z) =  $\Big(m(x,y,z),n(x,y,z),p(x,y,z)\Big).$ Ξ

**We define the divergence of the vector field as:**

$$
divField(x, y, z) = \frac{\partial m}{\partial x} + \frac{\partial n}{\partial y} + \frac{\partial p}{\partial z}
$$
  
=  $D[m[x, y, z], x] + D[n[x, y, z], y] + D[p[x, y, z], z]$ 

### Lesson 12: The Divergence Theorem (Using Traditional Notation)

Let V be a solid in three dimensions with boundary surface (skin) S with no singularities on the interior region V of S. Then the net flow of the vector field F(x,y,z) *ACROSS* the closed surface is measured by:

$$
\oiint_S \left( F \bullet n \right) dS = \iiint_V \left( \nabla \bullet F \right) dV
$$

Let 
$$
F(x, y, z) = (m(x, y, z), n(x, y, z), p(x, y, z)).
$$
  
\nLet  $\nabla = \left(\frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z}\right)$  be known as "del", or the differential operator.  
\nNote  $divField(x, y, z) = \nabla \cdot \mathbf{F} = \frac{\partial m}{\partial x} + \frac{\partial n}{\partial y} + \frac{\partial p}{\partial z}$ .  
\nFinally, let  $n =$  outeruniformal.

### Lesson 13: The Net Flow of A Vector Field ALONG a Curve

- Lesson 12 was about constructing a three-dimensional analog of using the Gauss-Green Theorem to compute the net flow of a vector field **ACROSS** a **SURFACE**. All we did was upgrade to a surface, and extend the definition of divergence to three dimensions.
- Lesson 13 is all about constructing a three-dimensional analog of the net flow of a vector field **ALONG** a **CURVE**.

Let's begin by reviewing how we did this in 2-dimensions for an **OPEN** curve:

Lesson 8: Measuring the Net Flow of a Vector Field ALONG an OPEN Curve in 2-Dimensions

Recall that if C is an open curve, then we can't use the Gauss-Green Theorem. We are stuck computing an old-fashioned line integral:

```
C
        b
         a
        C
  Field(x,y) unittan ds
          Field(x(t), y(t)) • (x '(t), y '(t))dt
     = \mathsf{m}(x,y)dx + \mathsf{n}(x,y)dy\bullet= 1 Field( X( T), V( T)) \bullet\int\int\int
```
Lesson 13: Measuring the Net Flow of a Vector Field ALONG an OPEN Curve in 3-Dimensions

Extending the idea of a line integral (the flow of a 3D vector field along a curve living in 3D) is not particularly difficult. Here it is:

```
C
      b
      a
      C
 Field(x,y,z) unittan ds

    Field(x(t),y(t),z(t)) (x'(t),y'(t),z'(t))dt

    m(x,y,z)dx n(x,y,z)dy p(x,y,z)dz

\int\int\int
```
If this integral is positive, the net flow of the vector field<br>along the curve is WITH the direction of the parameterization.<br>If this integral is negative, the net flow of the vector field<br>along the curve is AGAINST the di **along the curve is WITH the direction of the parameterization. If this integral is negative, the net flow of the vector field along the curve is AGAINST the direction of the parameterization.** 

Example 1: The Net Flow of a Vector Field ALONG an OPEN Curve in 3-Dimensions

Let 
$$
P(t) = (x(t), y(t), z(t)) = (t, 2t, 4\cos(t))
$$
 be a  
curve in 3D-space for  $0 \le t \le 2\pi$ . Given  
Field(x,y,z) =  $(-z, x, y)$ , find the net flow of the  
vector field along the curve.  

$$
\int_{c} \text{Field}(x, y, z) \cdot \text{unittan ds} = \int_{0}^{2\pi} \text{Field}(x(t), y(t), z(t)) \cdot (x'(t), y'(t), z'(t)) dt
$$

$$
= \int_{0}^{2\pi} \Bigl(-4\cos(t), t, 2t\Bigr) \bullet \Bigl(1, 2, -4\sin(t)\Bigr) dt
$$

$$
=\int\limits_{0}^{2\pi}\Bigl(-4\cos(t)+2t-8t\sin(t)\Bigr)dt
$$

 $=16\pi+4\pi^2$ 

Created by Chris<sup>r</sup> vectors shown above. **Positive. The net flow of the vector field is with the direction of the tangent** 

Now that we constructed a three-dimensional analog of the net flow of a vector field **ALONG** an **OPEN** curve, we want to generalize the Gauss-Green Theorem so that we can handle the idea of the net flow of a vector field **ALONG** a **CLOSED** curve. This involves significantly more subtlety than you might think at first.

Let's begin by reviewing how we did this in 2 dimensions for a closed curve:

### Lesson 8 : Measuring the Net Flow of a Vector Field ALONG a Closed Curve

Let C be a closed curve with a counterclockwise parameterization. Then the net flow of the vector field *ALONG* the closed curve is measured by:

#### **Field(x,y) unittan ds**  $\pmb{\{\mathrm{f}}}$

**C**

$$
= \int_{a}^{b} Field(x(t), y(t)) \bullet (x'(t), y'(t)) dt
$$
  
= 
$$
\oint_{C} m(x, y) dx + n(x, y) dy
$$

Let region R be the interior of C. If the vector field has no singularities in R, then we can use Gauss-Green:

$$
= \iint_{R} \left( \frac{\partial n}{\partial x} - \frac{\partial m}{\partial y} \right) dx dy
$$
 Let  $rotField(x, y) = \frac{\partial n}{\partial x} - \frac{\partial m}{\partial y}$ .  

$$
= \iint rotField(x, y) dx dy
$$

```
R
= \iint rotField(x, y) dx dy
```
### Lesson 8 : The Net Flow of A Vector Field ALONG a Closed Curve:

Let C be a closed curve parameterized counterclockwise. Let Field(x,y) be a vector field with no singularities on the interior region R of C. Then:

$$
\oint_{C} Field(x, y) \cdot unit \tan ds = \iint_{R} rotfield dx dy
$$

This measures the net flow of the vector field *ALONG* the closed curve.

 $\partial \mathsf{n}$   $\partial$ = -- - -- = DIIII X, V I, X I - $\partial {\bf x} = \partial$ **We define the rotation of the vector field as:**  $\mathsf{rotField}(x,y) = \frac{\partial n}{\partial x} - \frac{\partial m}{\partial y} = \mathsf{D}[n[x,y],x] - \mathsf{D}[m[x,y],y]$ **x** *c*y

In the 2D case, we needed a counterclockwise parameterization of our curve. The notions of "counterclockwise" and "clockwise" can be problematic in three dimensions, so we need to address this issue!



- Imagine you were standing atop this surface. Are your tangent vectors clockwise or counterclockwise relative to you?
	- But now image you are standing on the bottom of the surface. Relative to you are the tangent vectors clockwise or counterclockwise?

We can sort this problem out in most situations using the "right" hand rule": Created by Christopher Grattoni. All rights reserved.

This gives us our fix. Just designate whatever *you* want to call the top side of the surface, and check that your parameterization is counterclockwise relative to that designation. You may want to pick a "top" that yields a counterclockwise parameterization with minimal work.



The vocabulary for a surface that we can designate a top side for is an "orientable" surface. Not all surfaces are orientable, so not all surfaces will be accessible to us using the material in this chapter. See the demo in the Supplemental Mathematica file!



- The Möbius Strip is perhaps the most famous non-orientable surface
	- Why did the chicken cross the Möbius Strip?
- To get to the same side!

Next, we are going to need a 3D analog of rotField. This is going to take a little bit of work:

So we've dealt with a few challenges so far:

- How do we define clockwise/counterclockwise in 3D?
	- Answer: Designate a "top" side. Be kind to yourself by picking your "top" to make your boundary curve have a counterclockwise parameterization.
- What if you can't designate a top side?
	- Answer: Then you're in trouble. We need to work with orientable surfaces with 2 distinct sides.
- How do we generalize the rotation of a 2D vector field, rotField(x,y), to 3D?
	- Answer: With a formula in the form of a 3-component vector that can capture the 3 planes of rotation that can occur.

What do we mean by 3 planes of rotation? Well, imagine a kayak in whitewater rapids.



Surface rotation (whirlpool) xy-rotation

Sideways rotation (Eskimo roll) yz-rotation

Forward rotation (hydraulic/hole) xz-rotation

Let's See How we Derived the Formula for "Across" and then Apply these ideas for "Along"

Notice that in Lesson 12, we were able to define divergence as a dot product with del, the differential operator:

Let 
$$
\nabla
$$
(x, y, z) = (m(x, y, z), n(x, y, z), p(x, y, z)).  
\nLet  $\nabla = \left(\frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z}\right)$  be known as "del", or the differential operator.  
\nThen divField(x, y, z) =  $\nabla \cdot \mathbf{F} = \frac{\partial \mathbf{m}}{\partial x} + \frac{\partial \mathbf{n}}{\partial y} + \frac{\partial \mathbf{p}}{\partial z}$ .

This allows us to compute the flow of a vector field ACROSS a closed surface.

$$
\oiint\limits_{S} \left( F \bullet n \right) dS = \iiint\limits_{V} \left( \nabla \bullet F \right) dV
$$

We can obtain our higher-dimensional analog to rotField in the same way, but by using a cross product. We will call this curl:

Define the curlField using a cross product:

Unime the curless that  $\text{Cov}(\mathbf{x}, \mathbf{y}, \mathbf{z}) = \left( \mathbf{m}(\mathbf{x}, \mathbf{y}, \mathbf{z}), \mathbf{n}(\mathbf{x}, \mathbf{y}, \mathbf{z}), \mathbf{p}(\mathbf{x}, \mathbf{y}, \mathbf{z}) \right)$  and let  $\nabla = \left( \frac{\partial}{\partial \mathbf{x}}, \frac{\partial}{\partial \mathbf{y}}, \frac{\partial}{\partial \mathbf{z}} \right)$  (also known as "del") EXECUTE DELIVERED EXECUTE:<br>  $= (m(x,y,z),n(x,y,z),p(x,y,z))$  and let  $\nabla = \left(\frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z}\right)$  (also known **i j k**  $\textsf{\textbf{curl}}\textsf{\textbf{Field}}(\textsf{\textbf{x}},\textsf{\textbf{y}},\textsf{\textbf{z}}) = \nabla \!\times\! \textsf{\textbf{F}}$ **x** *c*y *c*z **m n p**  $= \nabla \times \mathbf{F} = \begin{vmatrix} \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \end{vmatrix}$  $\partial {\bf x}$   $\partial {\bf v}$   $\partial$ **p**  $\partial$ n  $\partial$ m  $\partial$ p  $\partial$ n  $\partial$ m  $\frac{\partial m}{\partial x} - \frac{\partial p}{\partial y}$  $\frac{\mathbf{p}}{\mathbf{y}} - \frac{\partial \mathbf{u}}{\partial \mathbf{z}} \cdot \frac{\partial \mathbf{u}}{\partial \mathbf{z}} - \frac{\partial \mathbf{p}}{\partial \mathbf{x}} \cdot \frac{\partial \mathbf{u}}{\partial \mathbf{x}} - \frac{\partial \mathbf{u}}{\partial \mathbf{y}}$  $\begin{pmatrix} 1 & 1 & 1 \\ \partial \mathbf{p} & \partial \mathbf{n} & \partial \mathbf{m} & \partial \mathbf{p} & \partial \mathbf{m} & \partial \mathbf{m} \end{pmatrix}$  $= \left(\frac{\partial p}{\partial y} - \frac{\partial n}{\partial z} \cdot \frac{\partial m}{\partial z} - \frac{\partial p}{\partial x} \cdot \frac{\partial n}{\partial x} - \frac{\partial m}{\partial y}\right)$ 

**This should look like the rotation of the vector field, but redesigned to account for rotation in three different planes!**

Lesson 13: The Flow of A Vector Field ALONG a Closed Curve in 3-Dimensions: **Example 13:** The I<br> **ALONG a Closed (**<br> **curlField(x, y, z)** =  $\left(\frac{\partial}{\partial y}\right)$ <br>
The x-component of The y-<br>
curlField(x, y, z) causes curlField(x, y, z) causes curlField<br>
swirl on the yz-plane swirl of **curlField(x, y, z)** =  $\left(\frac{\partial \mathbf{p}}{\partial \mathbf{y}}\right)$ <br> **curlField(x, y, z)** =  $\left(\frac{\partial \mathbf{p}}{\partial \mathbf{y}}\right)$ <br> **curlField(x,y,z)** causes<br>
curlField(x,y,z) causes<br>
swirl on the yz-plane

 $\frac{\partial P}{\partial y} - \frac{\partial P}{\partial z} \frac{\partial W}{\partial z} - \frac{\partial P}{\partial x} \frac{\partial W}{\partial x} - \frac{\partial W}{\partial y}$  $\textbf{curlField(x,y,z)} = \left(\frac{\partial \mathbf{p}}{\partial t} - \frac{\partial \mathbf{m}}{\partial t} - \frac{\partial \mathbf{p}}{\partial t}, \frac{\partial \mathbf{m}}{\partial t} - \frac{\partial \mathbf{m}}{\partial t}\right)$ 

**swirl on the yz-plane**

**The y-component of curlField(x,y,z) causes swirl on the xz-plane**

**The z-component of curlField(x,y,z) causes swirl on the xy-plane**

 $\begin{pmatrix} \partial \mathbf{p} & \partial \mathbf{n} & \partial \mathbf{m} & \partial \mathbf{p} & \partial \mathbf{n} & \partial \mathbf{m} \end{pmatrix}$ 

**y**  $\sigma$ **z**  $\sigma$ **z**  $\sigma$ **x**  $\sigma$ **x**  $\sigma$ **y**  $\sigma$ 



### Making Sense of curlField

Let Field(x,y,z) be a vector field, and let V be a unit vector whose tail is at the point  $(x_0, y_0, z_0)$ :

If curlField(x<sub>0</sub>,y<sub>0</sub>,z<sub>0</sub>) • V > 0, then Field(x,y,z) delivers the point (x<sub>0</sub>,y<sub>0</sub>,z<sub>0</sub>). **a counterclockwise swirl to the unit vector, V, through**

If curlField(x<sub>0</sub>,y<sub>0</sub>,z<sub>0</sub>) • V < 0, then Field(x,y,z) delivers point (x<sub>0</sub>,y<sub>0</sub>,z<sub>0</sub>). **a clockwise swirl to the unit vector, V, through the** 

**0 0 0 If curlField(x ,y ,z ) V 0, then Field(x,y,z) delivers** (x<sub>o</sub>,y<sub>o</sub>,z<sub>o</sub>). **no swirl to the unit vector, V, through the point** 

### Example 2: Calculating curlField•V

**Example 2:** Calculating curlField-V  
\nGiven Field(x, y, z) = 
$$
(-z^2, x^2, y^3)
$$
 and  $V = \frac{(2,3,5)}{\sqrt{2^2 + 3^2 + 5^2}}$  with its tail at  
\nthe point  $(1, 0, -1)$ , find and interpret curlField $(1, 0, -1)$  • V :  
\ni) curlField(x, y, z) =  $\begin{vmatrix} i & j & k \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ -z^2 & x^2 & y^3 \end{vmatrix}$   
\n= i(3y<sup>2</sup> - 0) - j(0 - (-2z)) + k(2x - 0)  
\n= (3y<sup>2</sup> - 2z, 2x)  
\nii) curlField(1, 0, -1) = (0, 2, 2)  
\niii) curlField(1, 0, -1) • V = (0, 2, 2) •  $\frac{(2,3,5)}{\sqrt{2^2 + 3^2 + 5^2}}$  ≈ 2.596  
\nPositive, so the vector V feels a counterclockwise switch around it  
\nat the point  $(1, 0, -1)$ .

Stokes' Theorem: Computing the Net Flow of a Vector Field Along a CLOSED Curve in 3D **Let Field Field Along a CLOSED Curve in**<br>Let Field(x,y,z) =  $(m(x,y,z),n(x,y,z),p(x,y,z))$ . Then given

Let Field(x, y, z) = 
$$
(m(x, y, z), n(x, y, z), p(x, y, z))
$$
. Then given

**an orientable surface, R, with a boundary curve, C, parameterized in the counterclockwise direction such that Field(x,y,z) has no singularities on R, w e have:** an orientable surrace, **K, with a boundary curve, C, para**<br>in the counterclockwise direction such that Field(x,y,z)<br>singularities on R, we have:<br>∮Field(x, y, z) • unittan ds = ∬curlField(x, y, z) • topunitr **n the counterciockwise airection such that** Field(x,y,z) has no<br>ngularities on R, we have:<br>Field(x, y, z) • unittan ds = ∬ curlField(x, y, z) • topunitnormal dA

Note: curlField(x, y, z) = 
$$
\left(\frac{\partial p}{\partial y} - \frac{\partial n}{\partial z}, \frac{\partial m}{\partial z} - \frac{\partial p}{\partial x}, \frac{\partial n}{\partial x} - \frac{\partial m}{\partial y}\right)
$$

boundary curve using the right-hand rule as your guide. **Note: For this to work, you need your surface to be orientable. That is, you need to be able to designate a top side of the surface, and then get a counterclockwise parameterization of the** 

### Stokes' Theorem Using Traditional Notation:

Stokes' Theorem Using Traditional Notatio  
Let F(x,y,z) = (m(x,y,z),n(x,y,z),p(x,y,z)), 
$$
\nabla = \left(\frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z}\right)
$$
, and  
n = topunitnormal. Then given an orientable surface, R, with a

 $\begin{array}{c} \mathsf{d}\mathsf{x}\end{array}$  are top unit normal. Then given an orientable surface, R, with a boundary curve, C, with a counterclockwise parameterization **such that Field(x,y,z) has no singularities on R, we have:** =

boundary curve, C, with a counterclockwise parameterization  
such that Field(x,y,z) has no singularities on R, we have:  

$$
\oint_{C} F(x, y, z) \bullet unit \tan ds = \iint_{R} (\nabla \times F) \bullet \textbf{n} dA
$$

$$
\text{curlField}(x, y, z) = \nabla \times F = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ m & n & p \end{vmatrix} = \left(\frac{\partial p}{\partial y} - \frac{\partial n}{\partial z}, \frac{\partial m}{\partial z} - \frac{\partial p}{\partial x}, \frac{\partial n}{\partial x} - \frac{\partial m}{\partial y}\right)
$$

### Stokes' 3D Theorem Reduces to Gauss-Green in 2D: **Let F(x, y) =**  $(m(x,y),n(x,y))$  **be a 2D-vector field. We can embed it in**

 $\big(\mathsf{m}(\mathsf{x},\mathsf{y}),\mathsf{n}(\mathsf{x},\mathsf{y})\big)$  $= \big($  M(x, y), n(x, y), 0 $\big)$ Let F(x, y) =  $(m(x,y),n(x,y))$  be a 2D-vector field.<br>3D by writing F(x, y) =  $(m(x,y),n(x,y),0)$ . Hence: =

$$
\text{curlField}(x, y, z) = \nabla \times F = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ m & n & p \end{vmatrix} = \left(0, 0, \frac{\partial n}{\partial x} - \frac{\partial m}{\partial y}\right) = \left(0, 0, \text{rotField}(x, y)\right)
$$

**Further, let R be a 2D-region with boundary curve, C, parameterized** in the counterclockwise direction. We can embed this in 3D by thinking<br>of this as a flat surface in xyz-space sitting on the xy-plane. Hence, we<br>know that n = topunitnormal = (0,0,1). **of this as a flat surface in xyz-space sitting on the xy-plane. Hence, we** 

$$
\oint_{C} F(x, y) \bullet \text{unittan ds} = \iint_{R} (\nabla \times F) \bullet \text{n dA}
$$
\n
$$
= \iint_{R} \text{rotField}(x, y) dx dy
$$

### Example 3: Using Stokes' Theorem

Let Field(x, y, z) = 
$$
(y + z, x + z, y + x)
$$
 and let R be the orientable  
surface shown below with boundary curve C.  
curlField(x, y, z) =  $\left(\frac{\partial p}{\partial y} - \frac{\partial n}{\partial z}, \frac{\partial m}{\partial z} - \frac{\partial p}{\partial x}, \frac{\partial n}{\partial x} - \frac{\partial m}{\partial y}\right)$   
=  $\left(0, 0, 0\right)$   
  
 $\oint_c$  Field(x, y, z) = unittan ds =  $\iint_R$  curlField  $\bullet$  topunitnormal dA  
=  $\iint_R$  (0, 0, 0)  $\bullet$  topunitnormal dA  
=  $\bullet$ 

### So the net flow of the vector field along the curve C is 0.

### Stokes' Theorem in Practice

**Look at our formula below. If you get a parameterization for your surface, find normal(s,t), and go to the trouble of making sure that these are top normals, it is reasonable to use Stokes' Theorem. In practice, it is usually**  find normal(s,t), and go to the trouble of making sure that these are top<br>normals, it is <u>reasonable</u> to use Stokes' Theorem. In practice, it is usually<br>easier to do the line integral than the surface integral. We will mai easier to do the line integral than the surface integral. We will mainly use Stokes' Theorem when the curlField is always (0,0,0).

$$
\oint_{c} Field(x, y, z) \cdot unit \tan ds = \iint_{R} curl Field \cdot topunit \text{normal } dA
$$
\n
$$
= \int_{t_1}^{t_2} \int_{s_1}^{s_2} curl Field(x(s, t), y(s, t), z(s, t)) \cdot normal(s, t) ds dt
$$

normal(s, t) = 
$$
\left(\frac{\partial x}{\partial s}, \frac{\partial y}{\partial s}, \frac{\partial z}{\partial s}\right) \times \left(\frac{\partial x}{\partial t}, \frac{\partial y}{\partial t}, \frac{\partial z}{\partial t}\right)
$$
  
\ncurlField(x, y, z) =  $\left(\frac{\partial p}{\partial y} - \frac{\partial n}{\partial z}, \frac{\partial m}{\partial z} - \frac{\partial p}{\partial x}, \frac{\partial n}{\partial x} - \frac{\partial m}{\partial y}\right)$ 

### Lesson 4: The Gradient Vector

Let  $f(x_1, x_2, ..., x_n)$  be a function of n variables. Then the **gradient vector is defined as follows:**

$$
\nabla f = \left(\frac{\partial f}{\partial x_1}, \frac{\partial f}{\partial x_2}, \dots, \frac{\partial f}{\partial x_n}\right)
$$

**The gradient vector is designed to point in the direction of the greatest INITIAL increase.**

CI. TV IIJ PEI SUI IC **Notice that the gradient vector always lives in one dimension lower than function does.** 3D surface? 2D gradient vector. 2D<br>lower than function does. 3D surface? 2D gradient vector. 2D Notice that the gradient vector always lives in one dimension<br>lower than function does. 3D surface? 2D gradient vector. 2D<br>curve? 1D gradient vector. 4D hypersurface? 3D gradient vector.

### The Gradient Vector Through the Lens of "Del," The Differential Operator

**1**, **x**<sub>2</sub>, ..., **x**<sub>n</sub>  $-\frac{\partial}{\partial x_2}$ , ...,  $\frac{\partial}{\partial x_n}$ **<u>OI**</u> Del, The Differential Operator<br>Let f(x<sub>1</sub>, x<sub>2</sub>,..., x<sub>n</sub>) be a function of n variables and let  $\nabla = \left(\frac{\partial}{\partial x_1}, \frac{\partial}{\partial x_2}, ..., \frac{\partial}{\partial x_n}\right)$ . Operator<br> $\nabla = \left(\frac{\partial}{\partial x_1}, \frac{\partial}{\partial x_2}, ..., \frac{\partial}{\partial x_n}\right).$ 



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Lesson 5: The Gradient Points Towards the Direction of Greatest Initial Increase

#### $(x + y)^2$ **Compare the gradient field and**  $f(x,y) = \frac{x+y}{e^{x^2+y^2}}$ **:**  $e^{x^2 +}$  $\ddot{+}$ =



#### **Following the gradient (usually) gets us to local mins/maxes.**

### Lesson 13: The Gradient Points Towards the Direction of Greatest Initial Increase

**2 2 2 x y z x y z f(x,y,z) . Now, f(x,y,z) is a 3-dimensional vector e Now consider** <u>of Greatest Initi $\frac{x+y+z}{e^{x^2+y^2+z^2}}$ .</u> Now,  $\nabla f(x,y,z)$  is

**field and f(x,y,z) is a 4-dimensional hypersurface. Your best bet is to think** of f(x, y, z) as a temperature function with local maximums being little hot **spots and local minimums being little cold spots. The gradient points you to these locations:**

at  $\big($ 0.408,0.408,0.408 $\big)$ . You can  $\big)$ **We can use FindMaximum in Mathematica to find a hot spot also see this from the plot of the vector field.**





A vector field, Field(x,y) = (m(x, y), n(x, y)), is a gradient<br>field if and only if the vector field has no singularities and: =

#### $\partial$ **x**  $\partial$ m  $\partial$ n Equivalently: rotField $(x, y) = 0$

### **Proof of "if" Part of Theorem:**

 $\left(f_{x},f_{y}\right)$ Proof of "if" Part of Theorem:<br>If Field(x,y) is a gradient field, then Field(x,y)=(f<sub>x</sub>,f<sub>y</sub>).

If Field(x,y)  
So 
$$
f_{xy} = f_{yx}
$$
.

### Lesson 13: The 3D Gradient Test

<u>A vector field, Field(x, y, z)</u> = (m(x, y, z), n(x, y, z), p(x, y, z)), is a gradient **field if and only if the vector field has no singularities and:** =

$$
curlField(x, y, z) = (0, 0, 0)
$$

$$
\text{curlField}(x, y, z) = \left(\frac{\partial p}{\partial y} - \frac{\partial n}{\partial z}, \frac{\partial m}{\partial z} - \frac{\partial p}{\partial x}, \frac{\partial n}{\partial x} - \frac{\partial m}{\partial y}\right)
$$
  
Outline of "if" Direction of Proof: For a function f(x,y,z), we would have to show that

**Outline of "if" Direction of Proof: For a function 
$$
f(x,y,z)
$$
, we would have to show that  
the gradient field,  $\nabla f = \left(\frac{\partial f}{\partial x}, \frac{\partial f}{\partial y}, \frac{\partial f}{\partial z}\right)$ , has curlField = (0,0,0).  

$$
\nabla \times \nabla f = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \frac{\partial f}{\partial x} & \frac{\partial f}{\partial y} & \frac{\partial f}{\partial z} \\ \frac{\partial f}{\partial x} & \frac{\partial f}{\partial y} & \frac{\partial f}{\partial z} \end{vmatrix} = (0,0,0)
$$**



 $\big(\mathsf{m}(\mathsf{x},\mathsf{y}),\mathsf{n}(\mathsf{x},\mathsf{y})\big)$ simple closed curve with a parameterization  $(x(t),y(t))$  for  $a \le t \le b$ . Let Field(x,y)= $(m(x,y),n(x,y))$  be a gradient field, and let C be a<br>simple closed curve with a parameterization (x(t),y(t)) for a  $\leq$  t  $\leq$  b.

$$
1) \int\limits_a^b \text{Field}(x(t), y(t)) \bullet (x'(t), y'(t)) dt = 0
$$

$$
2) \oint_C m(x, y) dx + n(x, y) dy = 0
$$

**3) The net flow of a gradient field** 



# along a simple closed curve is 0.<br> **Is the flow of a gradient field ACROSS a closed curve 0?**

### Lesson 13: The Net Flow of a Gradient Field Along a Closed Curve in 3D

**Let Field Along a Closed Curve in 3D**<br>Let Field(x,y,z)=(m(x,y,z),n(x,y,z),p(x,y,z)) be a gradient field, and let C Let Field(x,y,z)= $(m(x,y,z),n(x,y,z),p(x,y,z))$  be a gradient field, and let C<br>be a simple closed curve with a parameterization (x(t), y(t), z(t)) for a  $\leq$  t  $\leq$  b.

1) 
$$
\int_{a} \text{Field}(x(t), y(t), z(t)) \cdot (x'(t), y'(t), z'(t)) dt = 0
$$
  
2) 
$$
\oint_{C} m(x, y, z) dx + n(x, y, z) dy + p(x, y, z) dz = 0
$$

**b**

**3) The net flow of a gradient field along a simple closed curve in 3D is 0.**

**C R Stokes' Theorem: Field(x,y,z) unittan ds curl Field topunitnormal dA R**  $\int_0^{\infty}$  (0,0,0) • topunitnormal dA **0 Proof: If Field(x, y, z) is a gradient field, then curlField(x, y, z) = (0, 0, 0).** Created by Christopher Grattoni. All rights rese

## Lesson 13: The Net Flow of a Gradient

Field Along a Closed Curve in 3D **Let Field(x,y,z)= m(x,y),n(x,y),p(x,y) be a gradient field, and let C be a** Let Field(x,y,z)= $(m(x, y), n(x, y), p(x, y))$  be a gradient field, and let C be a simple closed curve with a parameterization  $(x(t), y(t), z(t))$  for  $a \le t \le b$ .

1) 
$$
\int_{a}^{b} \text{Field}(x(t), y(t), z(t)) \cdot (x'(t), y'(t), z'(t)) dt = 0
$$

$$
2) \oint_C m(x,y,z) dx + n(x,y,z) dy + p(x,y,z) dz = 0
$$

**3) The net flow of a gradient field along a simple closed curve in 3D is 0.**

**Your intuition here should be that if you start and end the same point, your net change in temperature is 0.**

The key is that you must have a **GRADIENT** field. **Note that this DOES NOT work for any old vector field.**

### Lesson 7: Path Independence for 2D-Gradient Field **1** Cradient Field<br>**1** Let Field(x,y)=  $(m(x,y),n(x,y))$  be a gradient field, and let C<sub>1</sub> and

Let Field(x,y)= $(m(x, y), n(x, y))$  be a gradient field, and let C<sub>1</sub> and<br>C<sub>2</sub> be different curves that share the same starting and ending point:

C<sub>2</sub> be different curves that share the same starting and ending point:

$$
\int_{C_1} m(x,y)dx + n(x,y)dy = \int_{C_2} m(x,y)dx + n(x,y)dy
$$



**A gradient field is said to be path independent. The net flow of the gradient field along any two curves connecting the same**

### Lesson 13: Path Independence for a 3D-Gradient Field **Let Field(x,y,z) m(x,y,z),n(x,y,z),p(x,y, z) be a gradient field, and let**

 $\big($  M(x, y, z), n(x, y, z), p(x, y, z) $\big)$ Let Field(x, y, z) = (m(x, y, z), n(x, y, z), p(x, y, z)) be a gradient field, and let<br>C<sub>1</sub> and C<sub>2</sub> be different curves that share the same starting and ending point: =

C<sub>1</sub> and C<sub>2</sub> be different curves that share the same starting and ending point:

Let Field(x, y, z) = (m(x, y, z), n(x, y, z), p(x, y, z)) be a gradient field, and let  
C<sub>1</sub> and C<sub>2</sub> be different curves that share the same starting and ending point:  

$$
\int_{C_1} m(x, y, z)dx + n(x, y, z)dy + p(x, y, z)dz = \int_{C_2} m(x, y, z)dx + n(x, y, z)dy + p(x, y, z)dz
$$

**Proof: Since Field(x, y, z) is a gradient field, the net flow of the vector field along a closed curve is 0:**

> **C** Then  $\oint$  Field(x, y, z)  $\bullet$  unittan ds = 0. Let C be the closed curve formed by  $C = C_1 \cup C_2$ . Let C be the closed curve formed by C = C<sub>1</sub> ∪ C<sub>2</sub>.<br>
> Then ∲Field(x, y, z) • unittan ds = 0.<br>
> ⇒  $\int_{c_1}$  Field(x, y, z) • unittan ds –  $\int_{c_2}$  Field(x, y, z) • unittan ds = 0  $\Rightarrow$   $\int$  Field(x, y, z)  $\bullet$  unittan ds =  $\int$  Field(x, y, z)  $\bullet$  unittan ds ⇒  $\int_{c_1}^{c_2}$  Field(x, y, z) • unittan ds –  $\int_{c_2}^{c_2}$  Field(x, y, z) • unittan ds<br>
> ⇒  $\int_{c_1}^{c_2}$  Field(x, y, z) • unittan ds =  $\int_{c_2}^{c_2}$  Field(x, y, z) • unittan ds Created by Christopher Grattoni. All rights reserved.

### Lesson 13: Path Independence for a 3D-Gradient Field **Let Field(x, y, z) = (m(x, y, z), n(x, y, z), p(x, y, z)) be a gradient field, and let**

 $\big($  M(x, y, z), n(x, y, z), p(x, y, z) $\big)$ Let Field(x, y, z) = (m(x, y, z), n(x, y, z), p(x, y, z)) be a gradient field, and let<br>C<sub>1</sub> and C<sub>2</sub> be different curves that share the same starting and ending point: =

C<sub>1</sub> and C<sub>2</sub> be different curves that share the same starting and ending point:

Let Field(x,y,z) =  $(m(x,y,z),n(x,y,z),p(x,y,z))$  be a gradient field, and let<br>C<sub>1</sub> and C<sub>2</sub> be different curves that share the same starting and ending point:<br> $\int_{\text{eq}} m(x,y,z)dx + n(x,y,z)dy + p(x,y,z)dz = \int_{\text{eq}} m(x,y,z)dx + n(x,y,z)dy + p(x,y,z)dz$ 

**A gradient field is said to be path independent. The net flow of the gradient field along any two curves that start and end at the same points is**  $\int_{C_1}$  m(x, y, z)dx + n(x, y, z)dy + p(x, y, z)dz =  $\int_{C_2}$ <br> **A** gradient field is said to k<br>
The net flow of the gradien<br>
curves that start and end a<br>
the same...